# STANDARD HORIZON

# FF525 50/200kHz BLACK BOX FISH FINDER



# **Operation Manual for:**











This guide relates to the following GPS CHART PLOTTERS: CP180, CP180i, CP190i, CP300i, CP300i, CP300i, CP300i, CP500, CP590 and CPV550.

For older GPS Chart Plotters, the manual is available for download at www.standardhorizon.com or by contacting Marine Product Support at 800-767-2450 ext 6800.



# FCC Compliance Statement

This device complies with Part 15 of the FCC limits for Class A digital devices. This equipment generates, uses and can radiate radio frequency energy and, if not installed or used in accordance with the instructions may cause harmful interference with radio communications.

There is no guarantee that interference will not occur in a particular instance. If this equipment does cause harmful interference to other equipment, try to correct the problem by relocating the equipment.

Consult an authorized STANDARD HORIZON dealer or other qualified service technician if the problem cannot be corrected. Operation is subject to the following conditions: (1) This device cannot cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

#### CAUTION

- The FF525 contains dangerous high-voltage circuits which only experienced technicians can handle.
- STANDARD HORIZON will not be liable for errors contained herein, or for incidental or consequential damages in connection with the performance or use of this material.
- Because we frequently update our software and applications, the pictures shown through this Owner's Manual may be slightly different from what you see.

#### WARNING

 When plugging in or unplugging a transducer to the FF525 make sure power is turned off.

#### WARNING

 This Owner' Manual is for GPS Chart Plotters with software version 16.50 and later.

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# 1. INTRODUCTION

This manual provides basic information in becoming familiar with the advanced functions of the FF525 before you start using it combined with the STANDARD HORIZON GPS Chart Plotters.

#### 1.0 CONVENTIONS USED

Please refer to the legend below:

[MENU]	If you see brackets around a bold and capital letter word this refers to a key press.
[CHART]	If you see brackets around a bold and small capital letter word this refers to a Soft Key press.
GENERAL SET	<b>FUP</b> When a word(s) is in bold capital letters and underlined, this refers to a menu selection

# 1.1 CHART PLOTTERS

item.

Any menu operation and functions activation in this Operation Manual is related to the following Chart Plotter models with software capable to operate with FF525. Whenever it is necessary, a note has been inserted for those models with operational differences.

- CP180
- CP180i
- CP190i
- CP300
- CP300i
- CP390i
- CPV350
- CP500CP590
- CPV550

## 1.2 GENERAL INFORMATION

#### PRODUCT SUPPORT INQUIRIES

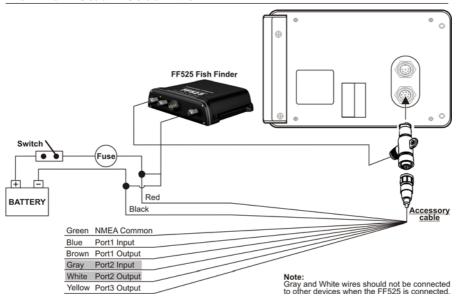
If you have any questions or comments:

- USA customers should contact STANDARD HORIZON on 714-827-7600 or by email marinetech@yaesu.com.
- UK customers should contact STANDARD HORIZON on 01962 866667 or email marinesales@standardhorizon.co.uk.
- European customers should contact their local dealer or distributor for support.

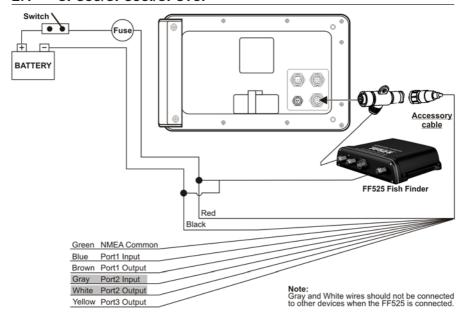
# 2. CONNECTING THE FF525

The FF525 must be properly installed according the following instructions to get the best possible performance. For more information on installation please see the FF525 Installation Manual.

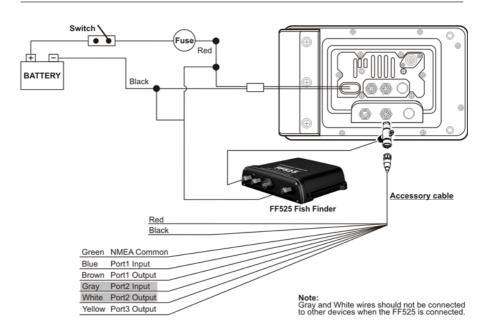
#### 2.0 CP180/CP180i/CP190i



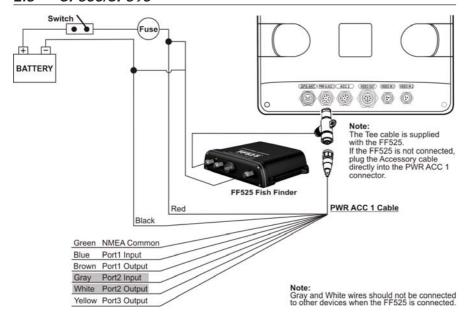
#### 2.1 CP300/CP300i/CP390i



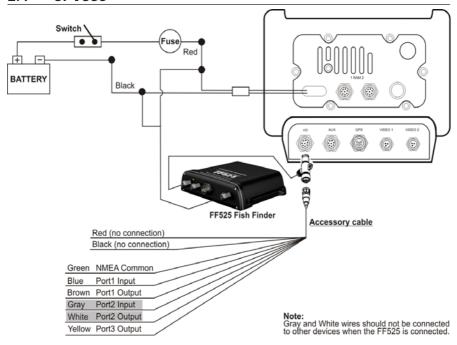
## 2.2 CPV350



## 2.3 CP500/CP590



#### 2.4 CPV550



#### NOTE

On software version 16.00.00R or later, port 2 of the GPS Chart Plotter has been set to FF525 by default. If the software in the GPS Chart Plotter is earlier than 16.00.00R, follow the steps below.

- From the Chart page, press [MENU], move the ShuttlePoint knob to highlight <u>SETUP</u> <u>MENU</u> and press [ENT].
- Move the ShuttlePoint knob to highlight <u>ADVANCED SETUP</u> and press [ENT] or move the ShuttlePoint knob to the right.
- Move the ShuttlePoint knob to highlight <u>IN/OUT CONNECTIONS</u> and press [ENT] or move the ShuttlePoint knob to the right.
- 4. Move the ShuttlePoint knob to highlight <u>PORT 2 INPUT</u> and press [ENT] or move the ShuttlePoint knob to the right.
- Move the ShuttlePoint knob up/down to select <u>FISH FINDER</u> and press [ENT] or move the ShuttlePoint knob to the right.
- 6. Press [CLR] or move the ShuttlePoint knob to the left until the Chart page is shown.

#### 3. **OPERATION**

#### UNDERSTANDING THE FISH FINDER PAGE 3.0

The display on STANDARD HORIZON GPS Chart Plotters shows a history of time of the echoes received by the transducer. The STANDARD HORIZON GPS Chart Plotters have a menu that allows adjustments to receiver sensitivity, depth range and scrolling speed of the Fish Finder display.

- (1) Warning message
- Fish Finder window
- Digital Depth
- Water temperature
- Shallow Alarm Bar
- 3 4 5 6 7 8 Range Bar
- Variable Depth Marker (VDM)
- A-Scope
- 9 Deep Alarm Bar
- 10 Transmit Frequency
- Color Bar

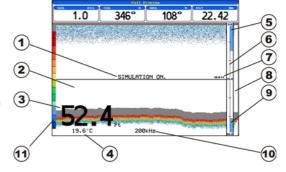


Figure 3.0 - The Fish Finder page

The following is a brief description of terms listed in the previous Figure:

# (1) Warning Message

Flashing label that is turned On when the echo sounder is in Simulation mode. The following is the list of the warning messages:

- SHALLOW WATER ALARM
- DEEP WATER ALARM
- HIGH WATER TEMP ALARM
- · LOW WATER TEMP ALARM
- WATER TEMP RATE ALARM
- FISH SPOT
- NO DATA, problem with connection between CP and Fish Finder Tee Cable

#### (2) Fish Finder window

Graphic presentation of sonar soundings recorded as a continuous bottom scrolling across the screen from right to left. Such recordings represent the image of the water beneath your boat, items appear as they pass under your transducer; the items on the right side of the screen are closer to you than those on the left. The correct interpretation of the Fish Finder page allows retrieving useful information about what is under the hoat

# (3) Digital Depth

Readout of the current bottom depth.

# (4) Water Temperature

Readout of the current water temperature returned by the temperature sensor included in DST520, DST521, DST523, DST525, DST526, DST527, DST528A.

## (5) Shallow Alarm Bar

Located on the right side of the Range Bar, the Shallow Alarm Bar shows the range outside of which the depth measurement will trigger a Shallow Alarm.

## (6) Range Bar

Vertical graduated bar, located along the right side of the screen. It is a scale which reflects the depth of the area being displayed.

## (7) Variable Depth Marker (VDM)

Horizontal line on to the Fish Finder page window with a depth label. Move the ShuttlePoint knob Up or Down to change the position of the VDM. The label displays the depth of the cursor position. The VDM can be moved to any location pinpointing the depth of a target.

# 8 A-Scope

Real time representation of fish and bottom features passing through the beam of the transducer, drawn as column of horizontal lines whose length and hue is proportional to the echo strength returned. The color of the echo strength depends on the selected display color. When the default palette is selected, the strongest sonar returns will be shown as red and weaker returns will be shown blue.

# (9) Deep Alarm Bar

Bar located on the left side of the Range Bar, showing the portion of the Echogram currently represented in the zoomed window (on the left part of the screen). It is turned On selecting the Echosounder Split page.

# (10) Transmit Frequency

Shows the selected depth transmit frequency. As a reference, 200 kHz selection is normally used to see targets in depth up to 400 Ft, and 50 kHz is used in water over 400 Ft.

# (11) Color Bar<sup>1</sup>

Colored scale located on the left side of the screen that shows the colors used in the Fish Finder page to represent the echoes strength. The color on the top of the bar FF525 represents the maximum echo strength, while the color on the bottom of the bar represents the minimum echo strength.

#### NOTE

Color Bar is displayed only if the Fish Finder is in 16 color (not 256 color) mode. Refer to Par. 4.0 FISH FINDER COLOR to change the color.

#### 3.1 UNDERSTANDING THE FISH FINDER DISPLAY

- (1) Fish
- (2) Thermocline
- (3) White Line
- Surface Clutter
- Structures
- 6 Bottom Echo Profile

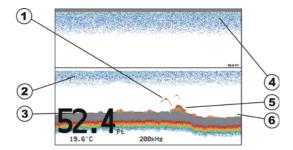


Figure 3.1 - The Fish Finder display

## 1 Fish

Fish are usually represented by small dots on the display when using 200 kHz and by arches when using 50 kHz.

## (2) Thermocline

Are the zones where two layers of different water temperatures meet. The greater the temperature differential, the denser the thermocline shows on the screen. Thermoclines are represented as horizontal stripes of noise. They are very important for fishing since often many species of game fish like to suspend in, just above, or just below the thermoclines.

# (3) White Line

The White Line shows the difference between hard, soft bottoms and even distinguishes between fish and structures located near the bottom. In this way it is easier to tell the difference between a hard and soft bottom and even to distinguish fish and structures located nearby the bottom.

#### (4) Surface Clutter

Appears like noise at the top of the screen extending many feet below the surface. It's caused by many things, including air bubbles, bait fish, plankton and algae.

## (5) Structures

Generally, the term "structure" is used to identify objects like wrecks and weeds rising from the bottom.

#### (6) Bottom Echo Profile

Bottom profile recorded by the FF525. When the echo sounder is set in Auto Range mode, the bottom is kept in the lower half in the display.

#### 3.2 DISPLAYING THE FISH FINDER PAGE

This section explains how to show and customize the selection of the Fish Finder display pages.

1. Press [MENU], if on the Fish Finder page press [MENU] two times.



Figure 3.2 - Example of Main Menu on CP590

 Move the ShuttlePoint knob to highlight <u>FISH FINDER</u> (or <u>RADAR/FISH</u> depending on the GPS Chart Plotter) and press [ENT].

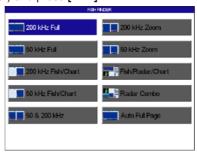


Figure 3.2a - Example of Fish Finder Page Selection menu on CP590

Move the ShuttlePoint knob to select the desired display and press [ENT]. The page options are shown in the following paragraphs.

# 3.2.0 Auto Full Page

When this page is selected, the FF525 automatically changes the transmit frequency to show depths. Automatic switching occurs when depth of water is less than 400 Ft (200 kHz) and greater than 400 Ft (50 kHz).

# 3.2.1 200 kHz Full, 50 kHz Full and 50&200 kHz Display Pages

Allows the user to setup the GPS Chart Plotters display to show 200 kHz, 50 kHz or 200/ 50 kHz split screen Fish Finder.

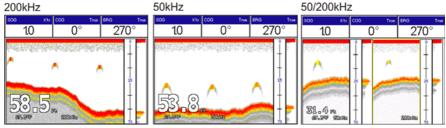


Figure 3.2.1 - Full Display pages

## 3.2.2 200 kHz and 50 kHz Zoom Pages

Allows the user to zoom into the 200 kHz or 50 kHz Fish Finder display to show detail of the area selected by the VDM (Variable Depth Marker). Referring to Figure 3.2.2, the left display shows the zoomed display and the right display shown the unzoomed display.

To select the area to be zoomed in move the ShuttlePoint knob Up or Down which moves the VDM line.

To zoom In or Out, press **[ZOOM IN]** or **[ZOOM OUT]** or, on the CPV350 and CPV550 press **[ZOOM]** and rotate the channel knob.

The zoom ranges are 2x and 4x the normal Fish Finder display.

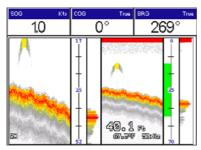


Figure 3.2.2 - Zoom Full Page

## 3.2.3 200 kHz and 50 kHz Fish/Chart Pages

Selects the display to show the Chart page on the left half of the screen and the Fish Finder on the right half of the screen. 200 kHz or 50 kHz Fish Finder can be selected on the right half of the display.

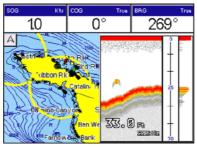


Figure 3.2.3 - Fish/Chart Page

With the focus on the Chart page the cursor may be moved and all chart menus can be selected. When focus is on the Fish Finder window the Variable Range Marker can be moved to see the depths of targets and Fish Finder menus can be accessed.

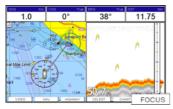
### 3.2.3.0 Focus on FISH/CHART Page

When the Fish/Chart page has been selected use **[FIND]** to place the focus on the Chart page or on the Fish Finder window.

#### For CP300/CP300i/CP390i/CPV350/CP500/CP590/CPV550

- 1. Select the 50 kHz or 200 kHz Fish/Chart page.
- 2. Press one of the Soft Keys under the display.

- 3. Press [Focus] to show the focus popup window.
- 4. Select Chart or Fish Finder using the ShuttlePoint knob and press [ENT].



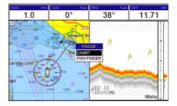


Figure 3.2.3.0 - Example of Chart/Fish page with [Focus] shown on CP390i

## 3.2.4 Radar Pages (EXCEPT CP180/CP180i/CP190i)

## 3.2.4.0 FISH/RADAR/CHART Page

Selects the GPS Chart Plotters display to show the Chart, the Fish Finder and the Radar page on the screen.

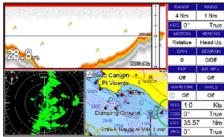


Figure 3.2.4.0 - Fish/Radar/Chart page on CP390i

## 3.2.4.1 RADAR COMBO Page

Selects the GPS Chart Plotters display to show the Chart, the Fish Finder, the Radar and the Highway page on the screen.

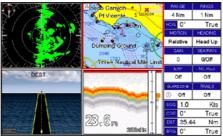


Figure 3.2.4.1 - Radar Combo page on CP390i

### 3.2.4.2 Focus Soft Key

When the Fish/Radar/Chart page or the Combo page has been selected, the active window is highlighted a "red" border around the window. The keyboard commands are related to that focused view. To move the focus to a different window follow the procedure:

- 1. Press any Soft Key. The Soft Key labels appear on the bottom of the screen.
- Press [Focus]. A popup window appears where the active focus window label is highlighted.

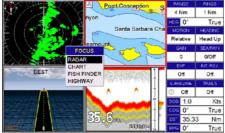


Figure 3.2.4.2 - Example of Combo Page with [Focus] shown on CP390i

Move the ShuttlePoint knob to highlight the desired window and press [ENT]. The red border is moved to the focused window.

# 3.3 SOFT KEY OPERATION (except CP180/CP180i/CP190i)

 Press any of the Soft Keys to show the key descriptions, then press the [200kHz] Soft Key if it has been customized (for detail see the next paragraph).



Figure 3.3 - Example of Fish Finder page selection by Soft Keys on CP390i

# 3.3.1 Customizing the Soft Keys

To customize a Soft Key, from Chart page:

- 1. Press any of the Soft Keys.
- 2. Press and hold the Soft Key you want to customize. The following menu appears:

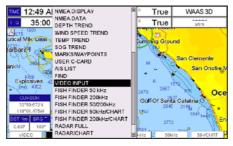


Figure 3.3.1 - Customizing Soft Keys on CP390i

3. Move the ShuttlePoint knob to the desired Fish Finder page and press [ENT].

# 4. FISH FINDER SETUP MENU

This section explains how to show the Fish Finder Setup menu and describe the Fish Finder Setup menu sub-options.

1. From the Full Fish Finder page, press [MENU]. The following menu appears:



Figure 4 - Fish Finder Setup menu

### 4.0 FISH FINDER COLOR

Allows you to choose the Fish Finder color between 16 and 256 colors.



Figure 4.0 - Fish Finder Color menu

#### 4.1 PRESETS

To simplfy menu selections, the FF525 has two presets that can be easily selected for fishing (Fish) or cruising (Cruise):



	FISH	CRUISE
Gain	Auto	Auto
Range mode	Auto	Auto
Gain offset	0%	10%
Shift	0	0
STC	Short	Short
Noise level	2	4
Scrolling Speed	10	10
Fish Symbols	Echo	Echo
A-Scope	On	On
Surface Declutter	4	4

Figure 4.1 - Presets menu (left) and table (right)

#### NOTE

For Gain and Gain Offset settings refer to Sensitivity menu (see Par. 4.3). For Range and Shift settings refer to Range menu (see Par. 4.4).

#### 4.2 FREQUENCY

Allows you to choose the Frequency among Auto, 50 kHz, 200 kHz or 50&200 kHz.



Figure 4.2 - Frequency menu

#### 4.3 GAIN MODE



Figure 4.3 - Gain Mode menu

#### 4.3.0 Auto Mode

Allows the Fish Finder to automatically adjust receiver Gain depending on water depth.

#### 4.3.1 Manual Mode

Allows the user to change the Gain manually to fine tune the FF525's receiver.

#### 4.4 RANGE MENU

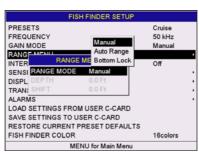


Figure 4.4 - Range menu

## 4.4.0 Range Mode

Selects among Manual, Auto Range and Bottom Lock.

· Manual Mode

Used to set the depth Range (from the surface) the Fish Finder display will show.

· Auto Range

The Fish Finder automatically determines the Range to keep the bottom visible in the lower bottom of the screen. In this mode, Shift is always set to 0.

Bottom Lock

The Bottom Lock function keeps the screen display locked onto a certain Range around the bottom. Let's say the bottom is 400 Ft and the Bottom Lock Range is set to display 30 Ft around the bottom, the screen (instead of displaying from 0 Ft to e.g. 450 Ft) will display only a Range of 30 Ft around the bottom, e.g. from 380 Ft to 410 Ft.

# 4.4.1 Depth

Moves the display from showing the bottom to the depth value entered.

## 4.4.2 Shift

Shifts the display from the bottom of the transducer to the depth value entered.

**Example:** Your vessel is in about 57 Ft of water, however there is fish suspended in 35 Ft of water. You want to display to 10 Ft area around the fish. Shift would be set to 30 Ft and Depth would be set to 40 Ft shown in the following example.

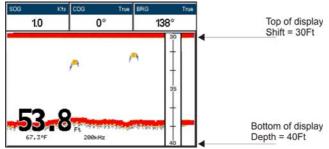


Figure 4.4.2 - Example of Depth and Shift

#### 4.5 INTERFERENCE REJECTION

Turns On or Off a filter to remove noise from other Fish Finder or Depth Sounders.



Figure 4.5 - Interference Rejection menu

#### 4.6 SENSITIVITY MENU

All settings in the Sensitivity menu are related to the selected Fish Finder transmit frequency (50 or 200 kHz).



Figure 4.6 - Sensitivity menu

#### 4.6.0 Gain

Allows you to control the Sensitivity of the unit's receiver from 0 to 100%. To see more detail, increase the receiver Sensitivity by selecting a higher Gain percentage. If there is too much detail or if the screen is cluttered, lowering the Sensitivity may increase the clarity of the display.

#### NOTE

When the Gain Mode option is set to Auto, the receivers Gain cannot be changed.

When the Gain Mode option is set to Manual, the Gain can be manually adjusted. When switching from Automatic to Manual Mode, the Gain + Offset value is copied into the Manual Gain setting of the receiver.

## 4.6.1 STC (Sensitivity Time Control)

The STC function attenuates echos from surface down to the specified STC depth by changing the sensitivity of the receiver, decreasing it near the surface and gradually increasing it as the depth increases. STC impacts bottom finding so it can be particularly useful to track a rocky sea bottom distinguishing it from mud in suspension over it.

For example when close to rivers outlet to the sea (consider to use at same time also Dual Frequency mode and White Line for an easier identification of real sea bottom), as well as to solve issues in false bottom detection when in presense of significant surface clutter (reading shallow, example 3 Ft).

Its default value is SHORT for the 200 kHz frequency and MID for the 50 kHz frequency. Such values are good in most conditions. However when navigating in very shallow waters it may be necessary to switch it to OFF, while in very deep waters with a lot of Surface Clutter it may be better to increase it to MID or LONG.

#### NOTE

In some situations it may be necessary to adjust the STC so the sounder can read through the surface noise and show the bottom. One indication that the STC needs to be changed is when the display intermittently changes the depth from the correct depth to a very shallow depth.

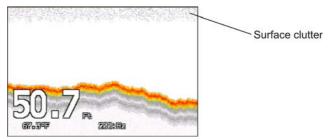


Figure 4.6.1 - STC - Surface Clutter

The STC can be changed from Short, Mid, Long and Custom.

## STC Length

This is the depth range which the STC operates. In custom mode it can be varied from 0 Ft to 1000 Ft (60 Ft or 255 Ft on previous software versions). In preset mode it's value is reported in the following table.

## · STC Strength

It is the starting attenuation value of the STC. It acts by attenuating the Gain of the given percentage value. In custom mode it can be varied from 0% to 100%. The STC effect is maximum near the surface, to mitigate the Surface Clutter and it progressively diminishes to 0 at the selected STC depth.

#### · Preset values table

	OFF	SHORT	MID	LONG
STC Depth (Ft)	1	60	60	255
STC Length	0	10%	30%	57%

Figure 4.6.1a - STC Preset values table

When in shallow water and the Fish Finder display is showing a bottom or digital readout deeper than the actual depth this situation may occur if STC is set to LONG or MID when the bottom is shallow. This issue may be resolved by adjusting the STC value to SHORT or even to OFF in very shallow waters.

When in DEEP WATER the Fish Finder display is showing a very shallow bottom or digital readout this may happen because in conditions of strong Surface Clutter the Fish Finder may erroneously look on to the Surface Clutter. To solve this situation try to increase the STC to LONG or to CUSTOM increasing the STC length and strength. When in DEEP WATER the Fish Finder doesn't see the bottom, this may happen because the bottom is out of range or is very near to the maximum depth that can be tracked by the Fish Finder. In the latter case this may happen if the bottom composition is soft as mud, if the sea conditions are bad, there are thermoclines or the water is full of suspended materials (silt, plankton). All these factors may affect considerably the performance of the Fish Finder to be able to see the bottom. In these cases change the RANGE MODE from AUTO to MANUAL Range and manually adjust the depth range until the bottom echo becomes visible on the Fish Finder display.

#### 4.6.2 Surface Noise Filter

An automatic filter that attempts to remove Surface Clutter that causes the screen to be filled up with strong return echoes just below the surface. It may seem that the same functionality could be achieved using on the STC control however there is main difference between such control in fact the STC control impacts the capability to detect and track the bottom and is not designed to cancel completely the surface noise, on the other side the Surface Noise Filter attempts to cancel completely the surface noise but it doesn't affect the capability to detect and track the bottom. Filter gradually attenuates surface noises. The Surface Noise Filter has 9 settings: OFF, 1, ..., 8. When set to 1 the Surface Noise is attenuated from surface down to a depth of 5 Ft, increasing the Surface Noise increases the depth in which the Surface Noise is attenuated as well as the attenuation level increases; when the preset is set to 8 the attenuation is maximum and is applied from surface level down to a depth of 255 Ft, as shown in the Surface Noise Filter Table reported below:

SURFACE NOISE FILTER DEPTH								
Preset	1	2	3	4	5	6	7	8
Depth (Ft)	5	10	15	20	30	60	130	255

Figure 4.6.2 - Surface Noise Filter Depth table

#### 4.7 DISPLAY SETUP

Allows the Fish Finder's display page appearance to be changed.

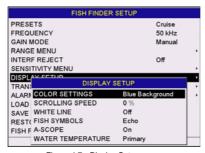
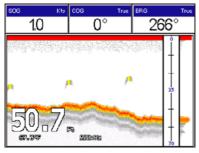


Figure 4.7 - Display Setup menu

## 4.7.0 Color Settings

Allows you to change the color of the Fish Finder display from Blue (default), White, Black, Gray scale.



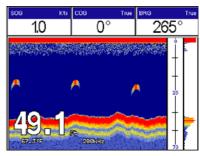


Figure 4.7.0 - White and Blue background examples

# 4.7.1 Scrolling Speed

Controls the rate the Fish Finder scrolls and updates the Fish Finder display.

### 4.7.2 White Line

Controls how the bottom type (hard or soft) is shown on the display. When the White Line is Off the bottom return will display as red. When the White Line is On it can be used to determine bottom hardness.

#### NOTE

The White Line option is not available in the 50 & 200 kHz page.

# 4.7.3 Fish Symbols

Controls the graphical representation of underwater-suspended targets.

Echo : shown as arches (echoes)

Icon + Echo : shown as arches with the Fish icon

Icon + Echo + Depth: shown as arches with the Fish icon and relative depth values

Echo + Depth : shown depth values

Icon : shown as Fish icons without the arches

Icon + Depth : shown as Fish icons and their relative depth values (shown accord-

ingly to currently selected depth unit)

# 4.7.4 A-Scope

Shows the real time display of the echo from the bottom.

# 4.7.5 Water Temperature

Allows selection between:

a. the temperature sensor in the depth transducer

or

b. an external temp sensor connected to the Optional Connection wires.

#### 4.8 TRANSDUCER SETUP

This menu allows you to calibrate the speed through the water, water temperature and the keel/prop offset of the transducer.

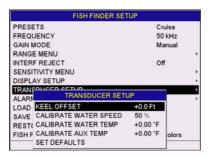


Figure 4.8 - Transducer Setup menu

## 4.8.0 Keel Offset

The keel offset can be set to cause the Fish Finder to display an offset depth below the keel or the actual water depth from the surface. To setup to show the depth below the keel, enter a negative depth value or a positive depth to show offset from the transducers face to the water surface.

## 4.8.1 Calibrate Water Speed

Used to calibrate the Water Speed readings from the transducer. Adjustment can be made from -10% to +10%.

# 4.8.2 Calibrate Water Temp

Used to calibration on the Water Temperature sensor in the transducer.

# 4.8.3 Calibrate Aux Temp

 $Allows the \ calibration \ of the \ Aux\ Temperature\ sensor\ connected\ to\ the\ Optional\ Connection\ wires.$ 

#### 4.8.4 Set Defaults

Restores the factory settings.

#### 4.9 ALARMS

The Alarms menu allows you to define alarm settings for Shallow Alarm, Depth Alarm and Temperature Upper/Lower/Rate.

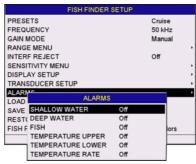


Figure 4.9 - Alarms menu

To set an Anchor Alarm, enter in a shallow water and deep water value above and below your actual anchoring depth. The alarm will sound when the depth becomes shallower or deeper than the settings.

#### 4.9.0 Shallow Water

Triggers an alarm when depth becomes shallower than the set depth.

## 4.9.1 Deep Water

Triggers an alarm when depth becomes deeper than the set depth.

#### 4.9.2 Fish

The Fish Alarm can be set to detect and alert you depending on the size of fish. The options are: Off, Small, Medium, Big and Huge. The alarm sounds if the set size (or bigger) is detected.

# 4.9.3 Temperature Upper

Triggers an alarm when the transducer reports a temperature above the set temperature.

# 4.9.4 Temperature Lower

Triggers an alarm when the transducer reports a temperature below the set temperature.

# 4.9.5 Temperature Rate

Triggers an alarm when the transducer reports a temperature variation rate above the set temperature.

## 4.10 SAVE SETTINGS TO USER C-CARD

This option saves the complete set of Fish Finder settings to an optional User C-CARD. This is useful to avoid the user having to retune up Fish Finder after a RAM Clear operation or a software update.



Figure 4.10 - C-Card - Save settings

#### 4.11 LOAD SETTINGS FROM USER C-CARD

This option loads the complete set of Fish Finder settings from the User C-CARD (Memory Card that may be used to backup the User Points and Tracks too).

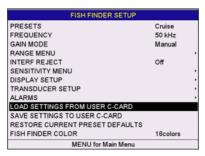


Figure 4.11 - C-Card - Load settings

#### 4.12 RESTORE CURRENT PRESET DEFAULTS

This option restores the default values only for the current presets (see Par. 4.1, Presets) and does not affect the other presets.



Figure 4.12 - C-Card - Restore settings

# 5. OPERATION TIPS

## 5.0 How can I set optimal operating parameters?

Optimal operating parameters can be set accordingly with the intended use of the Fish Finder, to quickly get optimal operational parameters for fishing it is may be best to select the FISH preset from the Fish Finder Setup menu, while for cruising it is may be best to select the CRUISE preset.

## 5.1 What are preset modes?

Preset modes are pre-defined settings of the Fish Finder operating parameters. You can use them to quickly set the Fish Finder in the most commonly used operating modes. These are:

- CRUISE: sets Fish Finder in Full Auto mode with the sensitivity settings (GAIN OFFSET, NOISE level and STC) optimized for displaying the bottom while underway.
- FISH : sets the Fish Finder in Full Auto mode with the sensitivity setting optimized for fish finding.

## 5.2 How can I restore the Fish Finder to factory default settings?

While the Fish Finder page is shown, press **[MENU]** and move the ShuttlePoint knob to Transducer Setup and press **[ENT]**. Move the ShuttlePoint knob to Set Defaults and press **[ENT]**. Press **[Confirm]** on the CP300/CP300i, CP390i, CPV350, CP500, CP590 and CPV550, or on the CP180/CP180i and CP190i press **[ENT]**. Note that this operation set all default settings, not only the working defaults.

# 5.3 Can I always leave the Fish Finder in Full Auto/(Auto Gain and Auto Range) mode?

Yes, but note that the Full Auto mode suits the 90% of the cases, however in extreme situations the Auto modes may fail and thus it is necessary to switch to the Manual mode.

### 5.4 What are extreme situations in which Auto modes may fail?

When the bottom is very deep, at high boat speed, when the bottom is very shallow (< 5Ft), when the water is full of materials in suspension, with bad sea conditions.

#### 5.5 What should I do if the Auto modes fail?

Failure of Auto modes can happen for various reasons. Hereafter you can find a range of possibilities.

# 5.6 Auto Range fails in very shallow waters displaying a digital depth readout deeper than the actual value. What should I do?

This usually happens if the STC is set to LONG or MID and the bottom is shallow or SHORT if the bottom is very shallow causing the Auto Range to hook to the second or third echo from the bottom (since in shallow waters the sound bounces more times back and forth the surface to the bottom). Try decreasing the STC value to SHORT in shallow waters or to switch it to VERY SHORT or OFF.

# 5.7 Auto Range fails, and the digital depth readout displays a very shallow reading. What should I do?

This usually happens if the STC is off or is set to a low value causing disturbance from Surface Clutter to be stronger than bottom echoes. Try increasing the STC value. As general rule STC has to be set as in shallow waters and LONG in depth waters.

# 5.8 Auto Range fails in very deep waters displaying a digital very shallow depth readout. What should I do?

The Fish Finder capability to detect the bottom decreases as the bottom depth increase. If the bottom composition is soft as mud, if the sea conditions are bad, if there are thermoclines or the water is full of materials in suspension it can further decrease thus causing the digital depth readout to fail. When this happens the Auto Range algorithm also fails. To recover from this situation it is necessary to switch to Manual Range mode and to set the Manual Depth mode. When Manual Depth mode is selected the algorithm that calculates the digital depth readout searches for the bottom within the range manually selected by the user. At this point it is necessary to increase manually the Range until the bottom becomes graphically visible. If the echoes from the bottom are strong enough, the Fish Finder shall look to the bottom giving a correct depth reading and shall be possible to return in Auto Range mode. Please note that if one or more of the conditions that reduce the echoes from the bottom listed above is true the bottom may be not visible at all, in this situation a strong thermocline or Surface Clutter may be interpreted by the Fish Finder as the bottom.

# 5.9 At a very shallow range upper half of the screen appears almost completely filled by the Surface Clutter. How can I eliminate it?

This is normal in shallow waters. To clean up the Surface Clutter without degrading the digital depth readout algorithm functionality there are two modes:

- If Surface Declutter = OFF it is possible to set the STC value to custom setting the STC length to the same size of the Surface Clutter, and increasing the STC strength until the image on the screen cleans up. Please note that in very shallow waters it is usually better to switch to Manual Gain mode to reduce Gain fluctuation due to rapidly changing bottom conditions.
- 2. Using Surface Declutter, increase the Surface Declutter value until the Surface Declutter disappears completely.

#### 5.10 Why do I never see fish in the range between 0 to 2Ft?

The minimum range of the Fish Finder is 2 Ft. In this interval the Fish Finder can detect neither the bottom nor any target.

#### 5.11 How can I reduce the Surface Clutter?

You can act by: properly setting the STC as described at 5.9 and also by increasing the NOISE LEVEL and reducing the GAIN or the GAIN OFFSET (if you are in Auto Gain mode). However please note that a strong attenuation of Surface Clutter may also reduce the capability to detect targets.

# 5.12 The Fish Finder is in Auto Gain mode but the picture display too many small targets, what shall I do to reduce the screen clutter?

Try increasing the NOISE LEVEL or decreasing the GAIN OFFSET.

# 5.13 In very shallow waters when the Auto Gain mode is selected there are fluctuations in the bottom profile width and its color representation. What should I do?

In very shallow waters the environment situation (bottom/water condition) changes very quickly thus causing the Auto Gain algorithm to create oscillations while trying to set optimal GAIN value for each situation. To avoid this it is advisable to switch to MANUAL GAIN mode and fine tune the GAIN to a fixed setting.

# 5.14 In very deep waters even setting the GAIN to its maximum value I cannot see the bottom what shall I do?

Try decreasing the NOISE LEVEL. If still the bottom is not visible there is nothing you can do, the bottom echo is simply too weak to be detected.

**5.15 GPS Chart Plotter shows no data when viewing the Fish Finder page.** This may be due to the FF525 having an issue. To confirm, listen to the depth transducer for the transmit pulse. If the pulse is not heard the FF525 is defective.

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